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Hence, the velocity is $v(t) = -gt + v_0 = -32t + 20$, and the first equation in (3.15) becomes $dx = -gt + v_0 dt$. Solving by integration, we get $x(t) = -\frac{1}{2}gt^2 + v_0 t + C_2 = -16t^2 + 20t + C_2$. Once more we evaluate this at $t = 0$ to show that $C_2 = x(0) = x_0 = 6$, the initial elevation of the ball.

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drawn. The MATLAB function `pplane5` is used to draw solutions of planar, autonomous systems having the form $x'=f(x,y)$, $y'=g(x,y)$.

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